Juvenile Salmon Response to Levee Repair on the Sacramento River

5 21053

4.81579 4.42105 4.02632 3.63158 3.23684 2.84211

2.44737 2.05263 1.65789 1.26316

0.868421 0.473684 0.078947 -0.315789 -0.710526

David Smith & R. Andrew Goodwin USACE - Engineer Research & Development Center, Vicksburg, MS

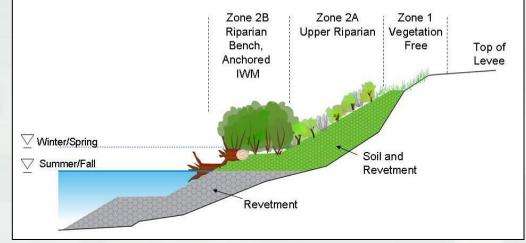
Brian Mulvey USACE Sacramento, CA



US Army Corps of Engineers BUILDING STRONG_®

Approach

- Construct enhanced levee repairs designed to promote salmonid rearing
- Many variations, commonly include woody material, native vegetation and shallow water benches
- Numerical "mock-up" of a river environment – populate with virtual fish
- Compare movement across scenarios





Modeling to Understand Behavior?

In Physics-based disciplines;

- replace natural system with equations
- study mathematical behavior
- draw conclusions about natural system

> Consider the question of "Fish behavior in response to flow"

- flow pattern description uses deterministic paradigm
- fish mechano-sensory system tightly coupled to fluid variables

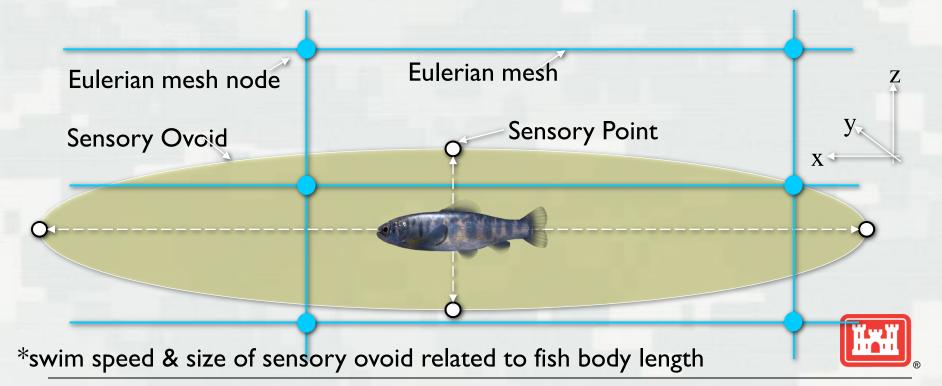
Statistical studies of "fish behavior in response to flow" are seldom conclusive – need a fresh approach



ELAMs: Understand & Forecast Fish Movement

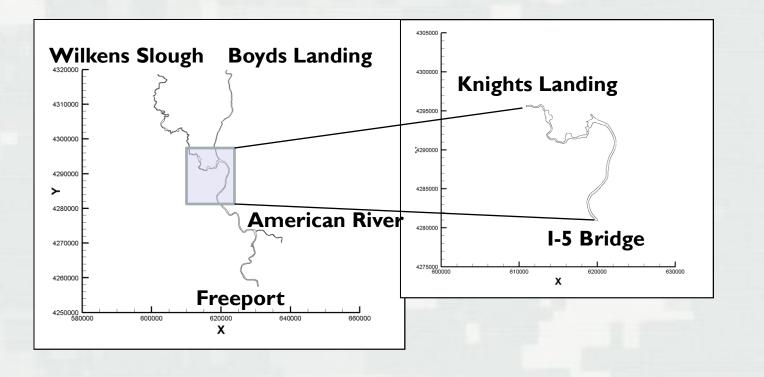
Important Attributes of the ELAM (Goodwin et al. 2014)

- capture temporal & spatial scales of complex biological processes
- venue for inter/trans-disciplinary education & integration
- information transformed to meet requirements of linked processes



CFD Model Attributes & Notes

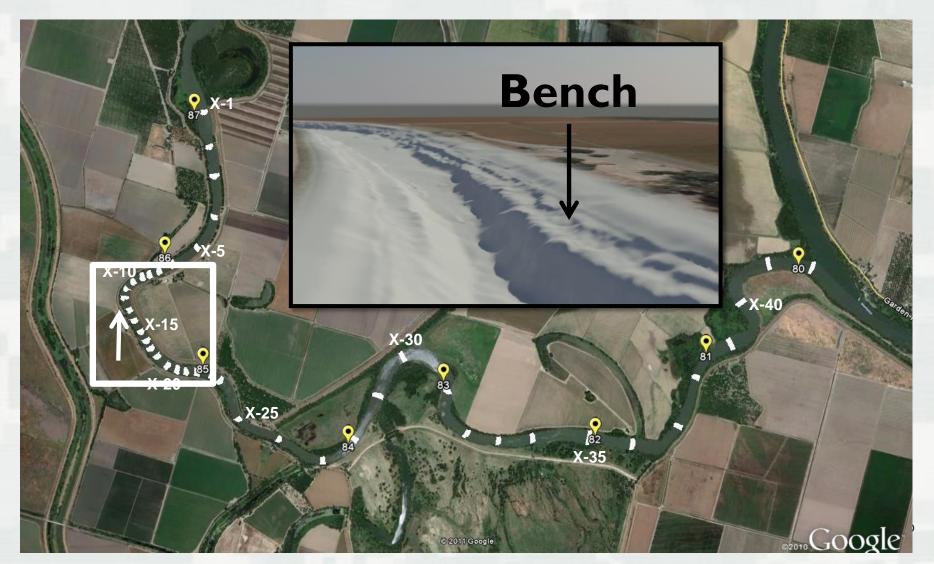
- ADH (USACE-ERDC), 192,467 elements, 2D, depth averaged
- Domain: 20 km long, December to April; 2010-2011; 2011-2012; 2012-2013



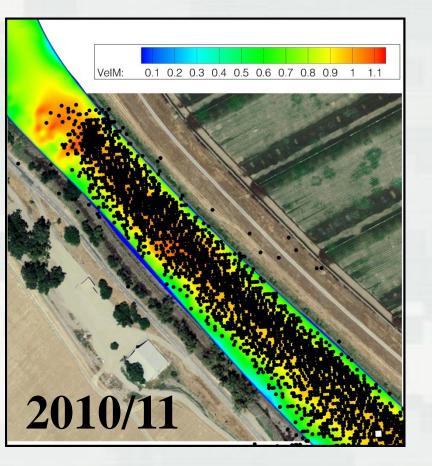
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Cross-section locations

42 cross-sections, ~0.2 mile spacing for most of reach Closer spacing (~300 ft) between RM85-86



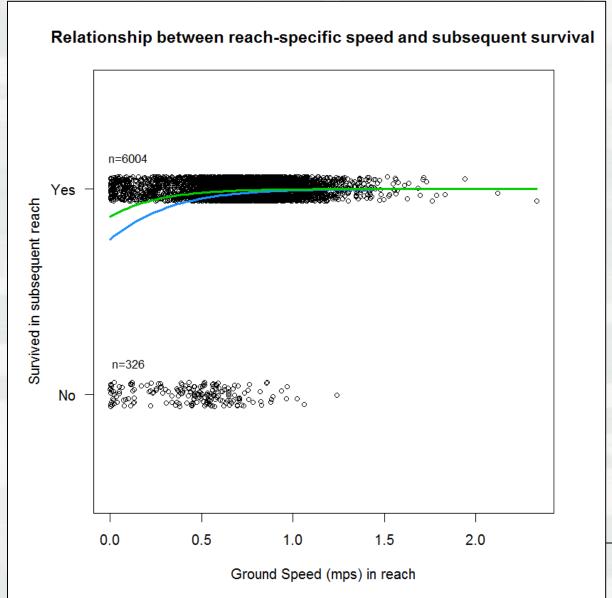
Telemetry data





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Slow fish survive at lower rates



- Blue line is a logistic model (general linear model, binomial family, with logit link)
- Green line is a general linear mixed model (same as above) where slope is allowed to vary with reach (i.e. reach is random variable)

 This model gave a better fit than the models where the intercept was allowed to vary with TagID

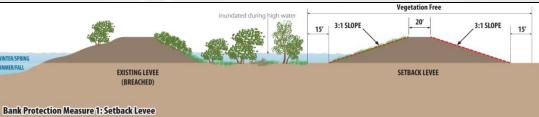


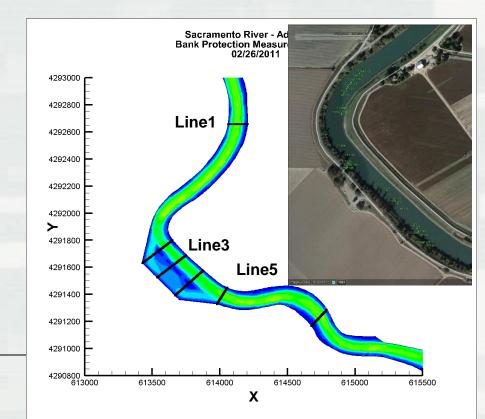
Observation: Habitat improvement designed to slow fish down

- Case study: Setback Levee
- Located at RM 85.6
- 1000 m long, 300 m deep, inundate at common winter flow but drain at lower flows



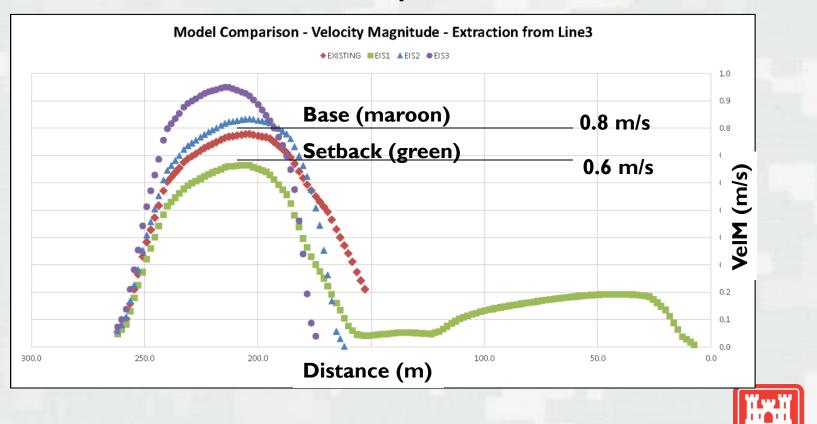
Setback levee animation





Velocity impacts of setback levee

Setback levee reduces velocity



Survival modeling – path length and travel time using ELAM

 Anderson et al. (2005) derived a survival model

- S = f(time and distance traveled)
- Implications for predator-prey interactions
- "XT-model"
- $S = \exp(-1/\lambda * sqrt(x^2 + \omega^2 t^2))$
- Troubling conclusion- setback levees reduce migratory survival

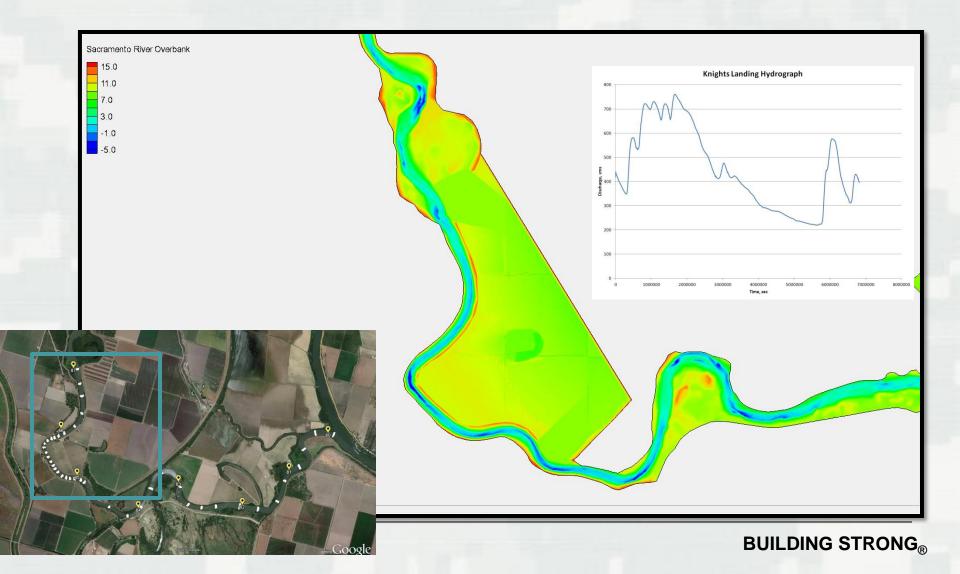
Short path – >99% survival Long path – 96% survival



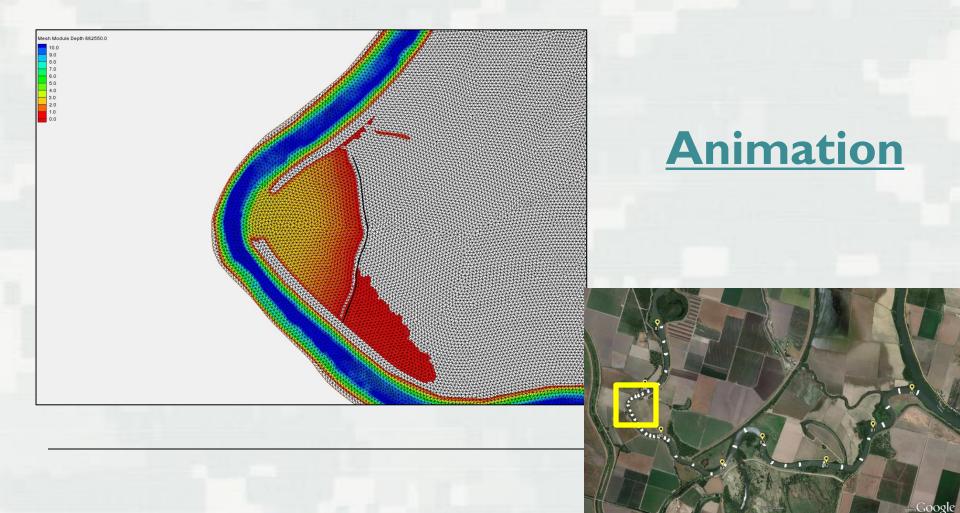




BIG setback



Geomorphological setback – big habitat benefit



Conclusions

- Simulation useful to understand setback levee survival outcomes
- Setback as designed only reduces water velocity and thus decreases migratory survival without producing rearing benefits
- Data was critical for defining basic boundaries of simulation
- Simulation suggest alternative setback levee designs more investigation needed
- Fish tracks in energetic environments are difficult and noisy technology limitations
- Predator contamination of data set present analysis challenges technology limitation
- We need behavioral data for rearing fish

